Compiling Distributed C++

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Abstract

Distributed C++ (DC++) is a language for writing parallel applications on loosely coupled distributed systems in C++. Its key idea is to extend the C++ class into 3 categories: gateway classes which act as communication and synchronization entry points between abstract processors, classes whose instances may be passed by value between abstract processors via gateways, and vanilla C++ classes. DC++ code is compiled to C++ code with calls to the DC++ runtime system. The DC++ compiler wraps gateway classes with handle classes so that remote procedure calls are transparent. It adds static variables to value classes and produces code which is used to marshal and unmarshal arguments when these value classes are used in remote procedure calls. Value classes are deep copied and preserve structure sharing. This paper shows DC++ compilation and performance.

1 Introduction

DC++ is designed to exploit loosely coupled distributed systems built by interconnecting multiple workstations through a local area network. DC++ is a distributed version of C++ [8] (this paper assumes knowledge of C++). DC++ provides a small number of simple extensions to C++: 2 built-in classes: `DcDomain` and `DcThread`; and 2 new categories of class instance usage: *gateways* between domains, and "value" instances which may be passed between domains through gateway member function invocation and return. The DC++ language is discussed in [6, 5]. This paper shows how DC++ is compiled. We will use the bounded buffer problem [1] as a running example throughout this paper. We include performance measurements for this example.

2 Domains — Abstract Processors

DC++ supports parallelism by providing 2 types: *domains* and *threads* ([13, 17]). A domain is a logically encapsulated address and control space, an *abstract processor*. A domain is similar to a monitor [11]: they ensure *mutual exclusion synchronization* by enforcing the rule that only one thread of control may be active in a domain at a time. If another thread attempts entry to an occupied domain, that thread will be queued on a FIFO queue for later entry when the domain becomes vacant. It differs from a monitor in that domains may be dynamically created and deleted. Further, a domain by itself does not have any entry points. Entry points may be dynamically created and deleted by creating *gateway* class instances into domains. A domain is created by specifying a physical processor number (0-based) on which to allocate the domain. For the bounded buffer example we will create 6 domains: one each for the 3 producers, one for the buffer, and one each for 2 consumers:

```
const num_producers = 3;
const num_consumers = 2;
DcDomain* pd[num_producers];
DcDomain* cd[num_consumers];
DcDomain* bd = new DcDomain(num_producers +
                            num_consumers);
for (int i = 0; i < num_producers; ++i)
    pd[i] = new DcDomain(i);
for (i = 0; i < num_consumers; ++i)
    cd[i] = new DcDomain(i + num_producers);
```

Since there may be more domains than actual physical processors, the domain is allocated on `i % DcNodeCount()`, where `DcNodeCount()` returns the 1-based number of physical processors available to the specific execution. This means that more than one domain may be explicitly (by the programmer) or implicitly (by the domain allocator) created on a processor. The DC++ runtime system supports multitasking so the programmer need not be concerned with these details.

3 Gateways — Domain Entry Points

A gateway is a system-wide unique "pointer" to an object created in a specific domain. It is treated as an ordinary C++ object: member function invocations on gateway objects result in remote procedure calls (RPCs) if that gateway resides in a different domain than the domain from which it is invoked. Otherwise a vanilla C++ member function invocation results. Since RPCs look identical to vanilla C++ member function invocations, redistribution of gateways is possible without program modification (modulo synchronization characteristics of the algorithm).

A gateway class is declared like a vanilla C++ class, except it inherits from `DcGateway`:

```
class Producer : public DcGateway {
  int     num_items; // Number items to produce.
  Buffer* buffer;    // Buffer to put them in.
public:
  Producer(int i, Buffer* b) {
    num_items = i, buffer = b;
  }
  void Produce() {
    while (num_items--) {
      buffer->Deposit(new Derived(num_items));
    }
  }
};
class Buffer : public DcGateway {
  unsigned  max_items; // Capacity of buffer.
  Derived** slots; // Array to contain items.
  unsigned  head;  // Where producer puts items.
  unsigned  tail;  // Where consumer gets items.
  unsigned  size;  // Number of items in buffer.
public:
  Buffer(int i){
    head = tail = size = 0;
    max_items = i;
    slots     = new Derived*[max_items];
    MakeDelayQueue(Buffer::Deposit);
    DQOpen(Buffer::Deposit);
    MakeDelayQueue(Buffer::Fetch);
  }
  void Deposit(Derived* i){
    slots[tail] = i;
    size++;
    tail = (tail + 1) % max_items;
    if (size > 0)
      DQOpen(Buffer::Fetch);
  }
  Derived* Fetch(){
    Derived* retval = slots[head];
    size--;
    head = (head + 1) % max_items;
    if (size < max_items)
      DQOpen(Buffer::Deposit);
    return retval;
  }
};
class Consumer : public DcGateway {
  int     num_items; // Number items to consume.
  Buffer* buffer;    // Buffer to get them from.
public:
  Consumer(int i, Buffer* b) {
    num_items = i, buffer = b;
  }
  void Consume() {
    while (num_items--) {
      Derived* i = buffer->Fetch();
      if (i->Data() == 0)
        return;
      spin();
    }
  }
};
```

The buffer has explicit *delay queues* associated with its `Deposit` and `Fetch` methods. Delay queues provide *condition synchronization*. If the delay queue is open, calls to the method proceed as normal. If the delay queue is closed then the calls are queued on a FIFO queue for later entry to the method when the queue is opened. A call (thread) waiting on a method's delay queue is not considered to have entered the domain. They are used in this example to ensure that producers only deposit items when there is room in the buffer, and that consumers only fetch items when there is one or more available.

A gateway instance is created in a specific domain by providing an optional domain argument as the first argument to the gateway's constructor. If not present the current domain is used:

```
Buffer*   b  = new Buffer(bd, 8);
Producer* p[num_producers];
Consumer* c[num_consumers];
for (i = 0; i < num_producers; ++i)
    p[i] = new Producer(pd[i], 25, b);
for (i = 0; i < num_consumers; ++i)
    c[i] = new Consumer(cd[i], 25, b);
```

Note that the type passed between the producer, buffer and consumer is `Derived*`. This type is a user defined "value" class and will be discussed later. Also note that the optional domain argument is not declared in the user's gateway class definition. This is handled by the compiler.

4 Threads

Concurrency is achieved by creating multiple threads of control. In the bounded buffer example,

threads are created for the producers and consumers, whereas the buffer is passively enclosed in a domain to ensure mutually exclusive access to it:

```
for (i = 0; i < num_consumers; ++i)
    new DcThread(c[i]->Consume());
for (i = 0; i < num_producers; ++i)
    new DcThread(p[i]->Produce());
```

Threads may return values when they terminate. These values may be used by the thread which created the new thread, and/or the termination of the created thread may be detected by the creating thread. This feature is not used in this example.

5 Compiling Gateways

The fundamental idea is to transform the program so that all references to user defined gateway classes are changed to references to compiler generated *handle classes*. Each user gateway class has an associated handle class which intercepts all method invocations. The handle class determines if the gateway method being invoked is for an instance in the same domain as the invoker. If so, it does a normal C++ method invocation. Otherwise, it marshals the arguments and does an RPC to the domain in which the gateway resides. Upon return it unmarshals the return value. The compiler generated handle class frees the programmer from these details and allows gateways to be redistributed without program modification. This section shows the details of the gateway compilation process.

A unique tag is created for all gateway classes in a program:

```
enum CLASS_TAGS {
        Consumer_TAG,
        Buffer_TAG,
        Producer_TAG,
};
```

These tags are used to indicate the type of object being made when that object is created remotely.

Each user gateway class is wrapped by a handle class:

```
class Buffer_W : public gateway {
public:
  Buffer_W(int i)
    : gateway(new Buffer(i)) {}
  Buffer_W(DcDomain* d, int i)
    : gateway(d,
              MakeRemoteObject(Buffer_TAG,
                               d, i)) {}
  Derived*  Fetch();
  void      Deposit(Derived*  );
};
```

For each constructor in the user class, 2 constructors are created in the handle class: one with a type signature identical to the user's definition, and one which adds a domain argument as the first parameter. In this way gateways may be created in the same domain or between domains.

The handle class inherits from **gateway**, whose definition is:

```
class gateway {
private:
  DcDomain* domain;  // domain where object lives
  DcObject* remote;  // remote object
  void*     local;   // local object
protected:
  DcDomain* domainGid() { return domain; }
  DcObject* remoteObj() { return remote; }
  void*     localObj()  { return local; }
  void*     localP()    { return local; }
  gateway(void* v) :
    domain(NULL), remote(NULL), local(v)    {}
  gateway(DcDomain* did, DcObject* oid) :
    domain(did), remote(oid), local(NULL) {}
};
```

When creating objects derived from **gateway**, a gateway is returned which either points to an instance in the domain or to an instance in a remote domain.

When the handle class constructor is given an optional domain it constructs the actual object on a remote node via the compiler generated `MakeRemoteObject` routine:

```
DcObject* MakeRemoteObject(unsigned type){
    void* v = NULL;
    switch (type) {
    case Consumer_TAG :
        v = new Consumer; break;
    case Buffer_TAG   :
        v = new Buffer;   break;
    case Producer_TAG :
        v = new Producer; break;
    default:
        DcError("Unknown object type");
    break;
    }
    return RegisterObject(v, DcThisDomain());
}
```

`RegisterObject` is a DC++ runtime system routine which places the actual pointer to the newly created object into an `OutTable` table, a table of entities which may be used remotely. It returns a `DcObject*` which is a special pointer type which is unique and valid

between domains. The bits of this pointer indicate the node on which the object resides and the index of the actual object pointer in that node's `OutTable` table.

This example is incomplete in that it doesn't show how arguments to constructors are handled remotely, and it only shows one constructor per class. If there is more than one constructor they are distinguished by their type signature. Constructor arguments are handled in a manner similar to arguments to methods (shown below).

A tag is created for each public method in the handle class (constructor tags not shown in example):

```
enum BufferPTR_METHOD_TAGS {
        DerivedptrBufferFetch_TAG,
        voidBufferDepositDerivedptr_TAG,
};
```

For each method in the user's original gateway definition an associated method is defined in the handle class:

```
void  Buffer_W::Deposit(Derived*  a3){
  if (localP())
    return ((Buffer_W*)localObj())->Deposit(a3);
  MsgBufId f = MakeMsgBuf(100);
  SetMsgBuf(f, 0, remoteObj());
  SetMsgBuf(f, 1, voidBufferDepositDerivedptr_TAG);
  PACK_voidBufferDepositDerivedptr_PARMS(f, &a3);
  ApplyWithinDomain(REMOTE_Buffer_HANDLER,
                    f, domainGid());
  DeleteMsgBuf(f);
}
Derived* Buffer_W::Fetch(){
  if (localP())
    return ((Buffer_W*)localObj())->Fetch();
  MsgBufId f = MakeMsgBuf(2);
  SetMsgBuf(f, 0, remoteObj());
  SetMsgBuf(f, 1, DerivedptrBufferFetch_TAG);
  MsgBufId fr = (MsgBufId)
        ApplyWithinDomain(REMOTE_Buffer_HANDLER,
                          f, domainGid());
  DeleteMsgBuf(f);
  Derived* result;
  UNPACK_DerivedptrBufferFetch_RETVAL(fr, &result);
  DeleteMsgBuf(fr);
  return result;
}
```

These handle methods are how transparent RPCs are achieved. If a `Buffer` handle instance is created in the same domain as the invoker of its constructor then a pointer to that local object is installed in the gateway's `local` method variable. When a handle method is invoked it first checks to see if the object is local. If so it avoids the overhead of RPC by invoking the local method. Otherwise it marshals the remote object reference, the method tag, any arguments, and then calls the RPC handler in the domain for that handle class via `ApplyWithinDomain`. `ApplyWithinDomain` is the blocking remote procedure call routine in the DC++ runtime system. When the RPC returns, it unmarshals the return value into a message buffer. The operation of compiler generated `PACK` and `UNPACK` marshaling routines is discussed later. They use runtime message buffers (`MsgBufId`) to contain object references, method tags, argument values, and return values.

A remote method handler is created for each handle class. The method tags are used to dispatch to the appropriate method when handling RPCs:

```
void* REMOTE_Buffer_HANDLER(MsgBufId f){
  Buffer* r = (Buffer*) OutTable(MsgBuf(f, 0));
  BufferPTR_METHOD_TAGS m = MsgBuf(f, 1);
  switch (m) {
  case DerivedptrBufferFetch_TAG : {
    DeleteMsgBuf(f);
    Derived* a4 = r->Fetch();
    MsgBufId fr =
          PACK_DerivedptrBufferFetch_RETVAL(&a4);
    return (void*) fr;
  }
  case voidBufferDepositDerivedptr_TAG : {
    DeleteMsgBuf(f);
    Derived*  a3;
    UNPACK_voidBufferDepositDerivedptr_PARMS(f,
                                             &a3);
    r->Deposit(a3);
    return NULL;
  }
  default:
    DcError("Unknown method");
  }
}
```

This routine dispatches to the appropriate method call, marshals the arguments from the message buffer and calls the associated user operation. Return values are placed in a message buffer to be used on the other end of the RPC.

6 Value Objects

Systems such as [2] provide primitives for sending and receiving data between processes, but require the programmer to pack and unpack aggregate data. Besides the gateway classes, which marshal and unmarshal arguments and return values, DC++ provides "value" classes so that programs may pass deep,

structure-preserving copies of value class instances between domains. A value object is a class which inherits from the built-in DC++ class `DcValue`:

```
class Base : public DcValue {
        int data;
public:
        Base(int i = 0) : data(i) { }
        int Data() { return data; }
};
class Contained : public DcValue {
        char c;
public:
        Contained(char _c = 't') : c(_c) { }
};
class Derived : public Base {
        Contained mi, *mp1, *mp2;
        double    d;
public:
        Derived(int    _i = 0,
                double _d = 0.0,
                char   c1 = 'w',
                char   c2 = 'x')
                : Base(_i),
                  mi(c1),
                  d(_d),
                  mp1(new Contained(c2)),
                  mp2(mp1) { }
        ~Derived() { delete mp1; }
};
```

(Note that member data `mp1` and `mp2` point to the same instance.)

Inheriting from `DcValue` indicates that when one of these objects is passed as an argument to, or return value from a gateway member function, it is to be totally copied. This means that any objects, pointers to objects, or built-in data types contained within the passed object, must be recursively copied *and* any structure sharing present via pointers must be preserved. Any member data objects or member data pointers to objects, must be objects which also derive from `DcValue` so the compiler can add the necessary support for the complete copy operation. The compiler handles C++ scalar types automatically.

Value objects may be passed-by-value freely between domains via gateway member function arguments and return values. This is seen in the example by the calls to the `Buffer` methods `Deposit` and `Fetch` which accept and return instances of the user defined `Derived` class. These routines actually pass and return `Derived*`. In this case, the object is still copied and the pointer to the newly created object on the receiving end is used rather than the original pointer.

7 Compiling Value Objects

7.1 Runtime Type Information

The compiler adds static variables and virtual functions to each user class which inherits from `DcValue`:

```
class Base : public DcValue {
        DECLARE_TYPE(Base);
        int data;
 public:
        Base(int i = 0) : data(i) { }
        int Data() { return data; }
};
```

The `DECLARE_TYPE` macro:

```
#define DECLARE_TYPE(name) \
 public: \
  virtual const TypeInfo* Type() const \
          { return &info_obj; } \
  static const TypeInfo*  Info() \
          { return &info_obj; } \
  virtual void    Writer(ostream&) const ; \
  static DcValue* Reader(istream&); \
  static name*    Read(istream& s) \
          { return (name*)DcValue::Read(s); } \
  name(istream&); \
private: \
  static  const TypeInfo  info_obj \
```

defines `Type` and `Info` methods used to obtain type information at runtime. This information is contained in the private static member data `info_obj`. `Type` is used to get this information given any instance which derives from `DcValue` (e.g., `some_instance->Type()`). `Info` is used to get this information if the type is known before hand (e.g., `Base::Info()`). These are used to obtain type-specific reader functions used when sending objects between domains.

7.2 Sending Objects Over Streams

The `Writer`, `Reader`, `Read` methods and the `name(istream&)` constructor are used to convert objects to/from linear byte streams for transmission and reception between domains. The compiler generates these for each type that directly or indirectly inherits from `DcValue`:

```
DEFINE_TYPE(Base);
DEFINE_TYPE(Contained);
DEFINE_TYPE(Derived);
```

The `DEFINE_TYPE` macro:

```
#define DEFINE_TYPE(name) \
  DcValue*       name::Reader(istream& s) \
```

```
        { return new name(s); } \
  const TypeInfo name::info_obj(STRINGIFY(name), \
                                name::Reader) \
```

defines the **Reader** method which uses the constructor from **istream** to create an instance of the class given a linear stream of bytes. It also initializes the static **info_obj** method data to contain the name of the class and a pointer to the class reader.

The compiler generates a **Writer** method and an **istream** constructor for each value class:

```
Base::Base(istream& s) : DcValue(s) {
        s >> data;
}
void Base::Writer(ostream& s) const {
        s << data << endl;
}
Contained::Contained(istream& s) : DcValue (s) {
        s >> c;
}
void Contained::Writer(ostream& s) const {
        s << c << endl;
}
Derived::Derived(istream& s)
        : Base(s),
          mi(s),
          mp1(Contained::Read(s)),
          mp2(Contained::Read(s))
{
        s >> d;
}
void Derived::Writer(ostream& s) const {
        Base::Writer(s);
        mi.Writer(s);
        mp1->Write(s);
        mp2->Write(s);
        s << d << endl;
}
```

Derived types first call the static **Writer** for their base classes (only one in this example). Then they write out instances using the **Writer** method of the instance. Pointers to instances are written using the **Write** method. **Write** keeps a table of pointers to preserve structure sharing. Built-in data types are written and read to and from a stream with the normal C++ **iostream** operators. Data is written and read in identical order.

7.3 Argument Marshaling

The compiler generated **Buffer_W::Deposit** method receives a **Derived*** as an argument. It converts this to a linear byte stream via the generated **PACK_voidBufferDepositDerivedptr_PARMS** routine. This routine uses the write operations to write into an output string stream:

```
void PACK_voidBufferDepositDerivedptr_PARMS(
                    MsgBufId f, Derived** a3){
        ostrstream strout;
        (*a3)->Write(strout);
        PackMsgBuf(strout.str());
}
```

Write puts a linear representation of the contents of the instance of **Derived** into the string output stream **strout**. The byte stream component of the stream is obtained with the C++ standard **strstream.h** routine **strout.str()**. This is given to the message buffer for transmission to another domain (potentially over a LAN). (It is the message buffer's job to delete the byte stream when it is no longer needed.)

On the receiving end, **REMOTE_Buffer_HANDLER** uses **UNPACK_voidBufferDepositDerivedptr_PARMS** to convert this byte stream representation back into an instance in memory:

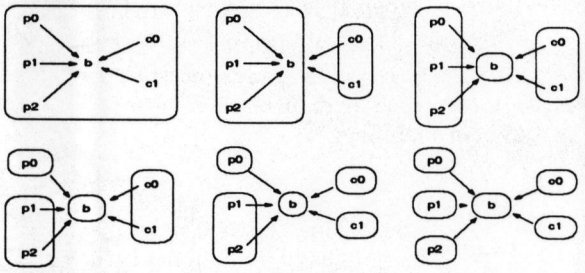
```
void UNPACK_voidBufferDepositDerivedptr_PARMS(
                    MsgBufId f, Derived** a3){
        int* fb = MsgBufBase(f);
        char* fbp = (char*) (fb + 2);
        istrstream instr(fbp, strlen(fbp) + 1);
        *a3 = Derived::Read(instr);
}
```

The message buffer's byte stream is obtained via **MsgBufBase**. It skips past the first two words (which contain the object reference and method tag) and uses the resulting stream and its length to create a standard **strstream.h istrstream** (input stream string). This stream is given to the static **Derived** class stream reader.

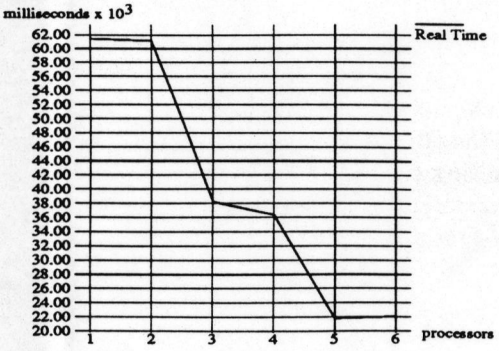
Derived::Read gives the stream to the input stream constructor for that type **Derived::Derived(istream&)** (defined above by **DEFINE_TYPE**). This in turn passes the stream first to the **Base** constructor and then the **Contained** constructor via **Base(s)** and **mi(s)** respectively. Since the next two fields, **mp1** and **mp2** are pointers, these are initialized from the stream via explicit calls to their static reader methods: **Contained::Read**. These explicit calls are necessary to detect structure sharing, whereas constructors are called when the method data contains an instance rather than a pointer. In this example, **mp1** and **mp2** do point to the same structure on the sending end, so this will be preserved on the receiving end. The reader routines keep a table of pointers for this purpose.

8 Performance Measurements

These measurements were taken on networked HP Series 9000, Model 370 Workstations. Communication between processors is via BSD sockets. For the measurements we created three producer threads, a single buffer, and two consumer threads. The producers produce 25 items each. The buffer capacity is eight. The consumers consume until they have consumed 25 items, or the `Data` item is `0`. The consumers spin (representing some work) for a period before attempting another fetch. The allocation of domains/gateways to processors, and the interprocessor communication pattern is:



pN, `b` and cN represent the producer, buffer, and consumer domains and their associated gateways. The circles represent real processors. The arrows represent caller/callee patterns.



The base case for both is for the producers, the buffer and the consumers to all multitask on a single processor. Speedup is achieved at three processors once the buffer is allocated to its own processor. At that point the consumers do not have to wait for a producer multitasking with the buffer to obtain access to the buffer. At four a slight speedup is achieved, but the producers must wait for the consumers to open space in the buffer. The best speed is obtained at five processors when the consumers each have their own processor. Adding another processor slightly increases the time since the producers produce faster than consumers can consume. The increased time is due to interprocessor communication overhead.

Other allocation patterns are possible, but are not the subject of this paper. Automated resource allocation is handled by [9]. Other problems such as the dining philosophers problem programmed in DC++ have shown realistic speedup [5].

9 Other Parallel C++ Languages

Another way to provide concurrency is to define an abstract class, **`Task`**, that implements the task abstraction. The constructor for **`Task`** creates a thread to animate the task. User-defined task classes may inherit from **`Task`**. This approach has been used to provide coroutine facilities [16, 14] and simple parallel facilities [7, 3, 4].

This "active object" approach has problems. (1) Code to start the task body appears in **`Task`**'s constructor. In C++, that code is executed first, before the constructors of any derived classes. Therefore, the new thread must be created in a blocked state, and must be unblocked after derived constructors finish. (2) Placing the task's body in its constructor is ruled out by inheritance, since a derived class must still execute the private data initialization of its base class but override the base class task body. A solution is to make the body a virtual `main` member function so derived tasks can replace it. (3) During initialization, while **`Task`**'s constructor is executing, the new task is considered to be an instance of class **`Task`**, not the actual derived task class being instantiated. Therefore, calling `main` in **`Task`**'s constructor will not execute the correct task body. DC++ avoids these problems by using "passive" objects. In fact, DC++ unbundles everything: threads are distinct from domains, which are themselves distinct from objects and gateways.

DC++ gateways (which provide RPC) are similar to "handles" in ESP [15]. However, use of ESP handles may require casting and may be visible to the programmer, whereas type-safety and the mechanics of gateways are handled by the DC++ compiler. CC++ [12] uses a combination of "global pointers" and "logical processor objects" to provide RPC. CC++ also employs single-assignment "sync" variables and the notion of "atomic" functions, whereas DC++ uses domains for synchronization and atomicity.

Systems such as [2], require the programmer to marshal values passed to remote procedures by hand. DC++ extends C++ such that values passed between domains are automatically (un)marshalled. DC++ extends this capability to user defined types through the concept of "value" classes, which may use all in-

heritance mechanisms. DC++ value types are similar to ObjectIO in the NIH Class Library [10].

10 Conclusions and Future Work

We have designed a distributed version of C++ based on concurrency mechanisms developed in our previous work in Concurrent Scheme [18]. We are continuing development of the DC++ compiler so it will fully automate the compilation process and detect illegal DC++ usages. The DC++ runtime system runs on homogeneous workstations. We plan to extend it to handle heterogeneous systems. The current performance measurements are very encouraging.

Acknowledgements

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